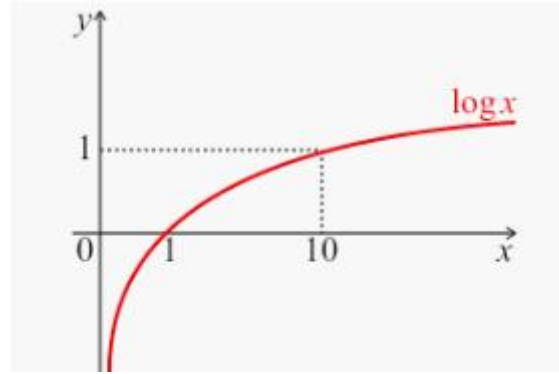


# Logarytmy

Definicja:

$$\log_a b = c \Leftrightarrow a^c = b,$$

$$a, b > 0, a \neq 1$$



Wybrane własności:

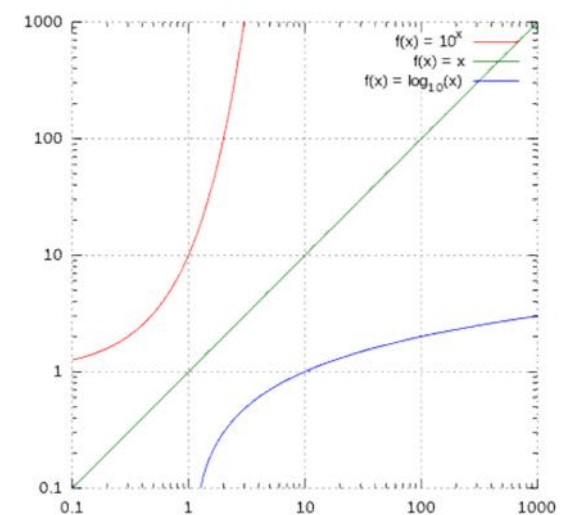
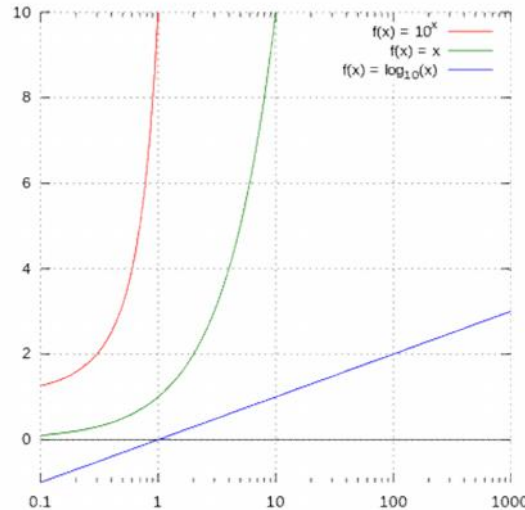
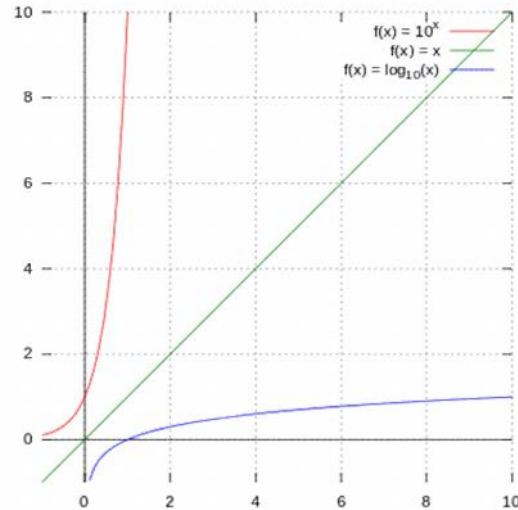
$$\log_a (bc) = \log_a b + \log_a c$$

$$\log_a \frac{1}{b} = -\log_a b$$

$$\log_a \frac{b}{c} = \log_a b - \log_a c$$

$$\log_a b^n = n \log_a b$$

Zastosowanie na skali logarymicznej



$$P_B = \log_{10} \left( \frac{P}{P_0} \right)$$

bel (zwiększenie mocy  $P$   
względem mocy  $P_0$ )

$$1 \text{ dB} = \frac{1}{10} \text{ B}$$

decybel

$$P_{\text{dB}} = 10 \log_{10} \left( \frac{P}{P_0} \right)$$

$$L [\text{dB}] = 10 \log_{10} \left( \frac{A^2}{A_0^2} \right) = 20 \log_{10} \left( \frac{A}{A_0} \right)$$

Amplituda sygnału jest proporcjonalna do kwadratu mocy

Przykład: Moc sygnału wyjściowego jest  $10^6$  większa od sygnału wejściowego:

$$\log_{10} \left( \frac{1.000.000 \cdot P_{\text{prg}}}{P_{\text{prg}}} \right) = \log \left( 10^6 \cdot \frac{P_{\text{prg}}}{P_{\text{prg}}} \right) = \log_{10} (10^6) = 6 \text{ B} = 60 \text{ dB}$$

## Transmitancja widmowa

$$G(s) = G(j\omega),$$

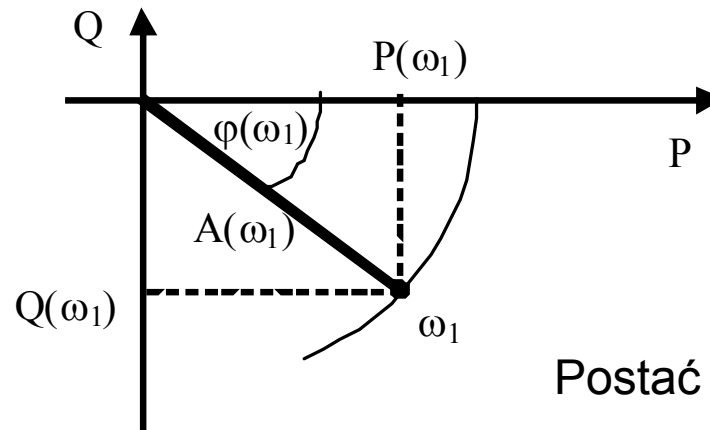
$$G(j\omega) = \frac{L(j\omega)}{M(j\omega)} = \frac{P_1(\omega) + jQ_1(\omega)}{P_2(\omega) + jQ_2(\omega)} = \frac{[P_1(\omega) + jQ_1(\omega)][P_2(\omega) - jQ_2(\omega)]}{P_2^2(\omega) + Q_2^2(\omega)}$$

$$G(j\omega) = P(\omega) + jQ(\omega)$$

$$G(j\omega) = A(\omega)e^{j\varphi(\omega)}$$

$$P(\omega) = \frac{P_1P_2 + Q_1Q_2}{P_2^2 + Q_2^2} \quad Q(\omega) = \frac{P_2Q_1 - P_1Q_2}{P_2^2 + Q_2^2}$$

$$A(\omega) = \sqrt{\frac{P_1^2 + Q_1^2}{P_2^2 + Q_2^2}} = \frac{A_1}{A_2} \quad \varphi(\omega) = \arctg \frac{P_2Q_1 - P_1Q_2}{P_1P_2 + Q_1Q_2}$$



Postać algebraiczna

$$G(j\omega) = P(\omega) + jQ(\omega)$$

$$P(\omega) = A(\omega) \cos[\varphi(\omega)]$$

$$Q(\omega) = A(\omega) \sin[\varphi(\omega)]$$

Postać wykładnicza

$$G(j\omega) = A(\omega)e^{j\varphi(\omega)}$$

$$A(\omega) = |G(j\omega)| = \sqrt{P^2(\omega) + Q^2(\omega)}$$

$$\varphi(\omega) = \arg[G(j\omega)] = \arctg \frac{Q(\omega)}{P(\omega)}$$

## Charakterystyki częstotliwościowe

$$G(j\omega) = \frac{L(j\omega)}{M(j\omega)} = P(\omega) + jQ(\omega) = A(\omega)e^{j\varphi(\omega)}$$

ch-ka rzeczywista

-  $P(\omega) = \text{Re}(G(j\omega))$

ch-ka urojona

-  $Q(\omega) = \text{Im}(G(j\omega))$

ch. amplitudowo-fazowa

-  $Q(P)$  (ch.Nyquista - dla ukł. otwartych)

ch. amplitudowa

-  $A(\omega) = |G(\omega)|$

ch. fazowa

-  $\varphi(\omega)$

logarytmiczna ch. modułu

-  $M(\omega) = 20 \lg A(\omega)$

logarytmiczna ch. fazy

-  $\varphi(\omega) = \text{arctg}(Q/P)$

log.ch.amplitudowo-fazowa

-  $M(\varphi)$

### Charakterystyki członów połączonych szeregowo

$$G(j\omega) = \prod_{i=1}^n G_i(j\omega) = \prod [A_i(\omega)e^{j\varphi_i(\omega)}]$$

- ch. amplitudowa

$$A(\omega) = \prod A_i(\omega)$$

- ch. fazowa

$$\varphi(\omega) = \sum \varphi_i(\omega)$$

- logarytmiczna ch.amplitudowa

$$M(\omega) = 20 \lg(\prod A_i(\omega)) = \sum M_i(\omega)$$

- logarytmiczna ch. fazy

$$\varphi(\omega) = \sum \varphi_i(\omega)$$

cz. proporcjonalny:

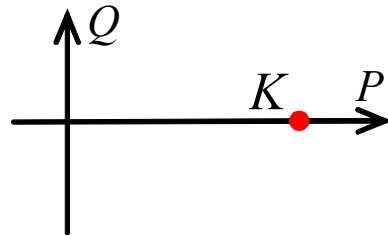
$$G(s) = K$$

$$G(j\omega) = K$$

$$P(\omega) + jQ(\omega) = A(\omega)e^{j\varphi(\omega)}$$
$$M(\omega) = 20\lg A(\omega)$$
$$\varphi(\omega) = \arctg(Q/P)$$

$$P(\omega) = K$$

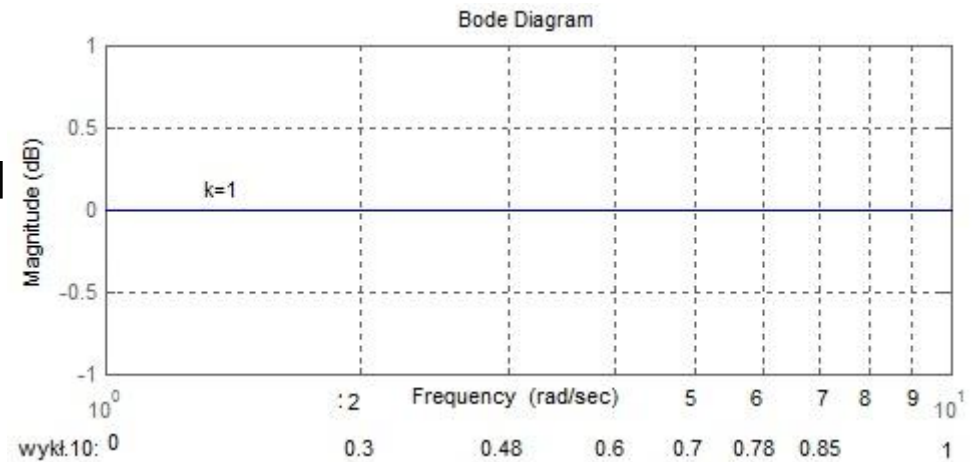
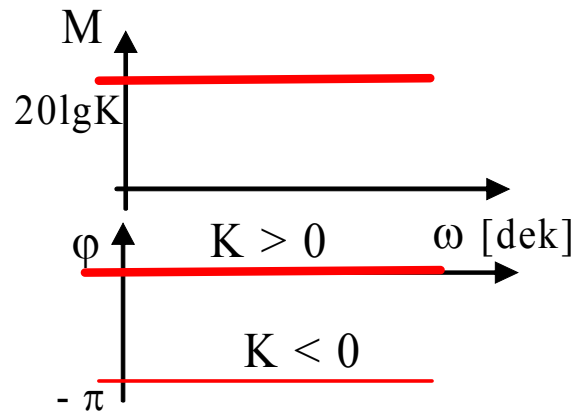
$$Q(\omega) = 0$$



$$A(\omega) = |K|$$

$$\varphi(\omega) = 0$$

$$M(\omega) = 20\lg|K|$$



cz. różniczkowy:

$$G(s) = sT_d$$

$$G(j\omega) = j\omega T_d$$

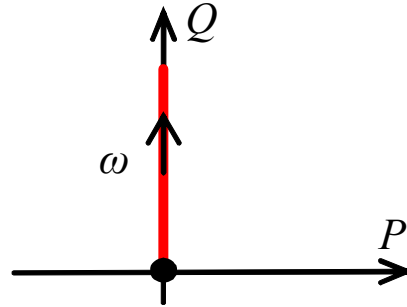
$$P(\omega) + jQ(\omega) = A(\omega)e^{j\varphi(\omega)}$$

$$M(\omega) = 20\lg A(\omega)$$

$$\varphi(\omega) = \text{arctg}(Q/P)$$

$$P(\omega) = 0$$

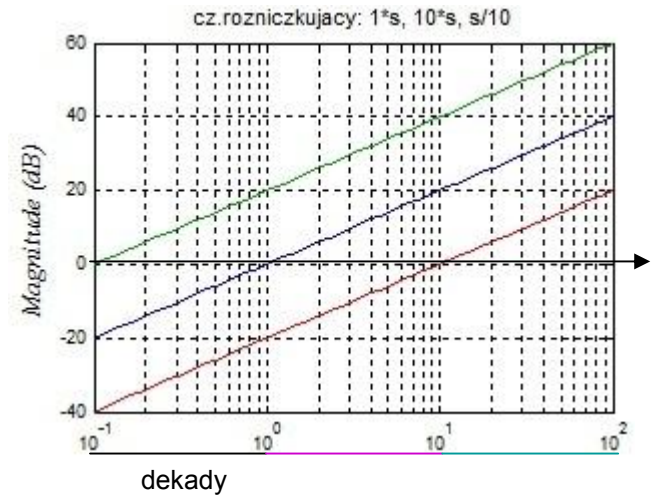
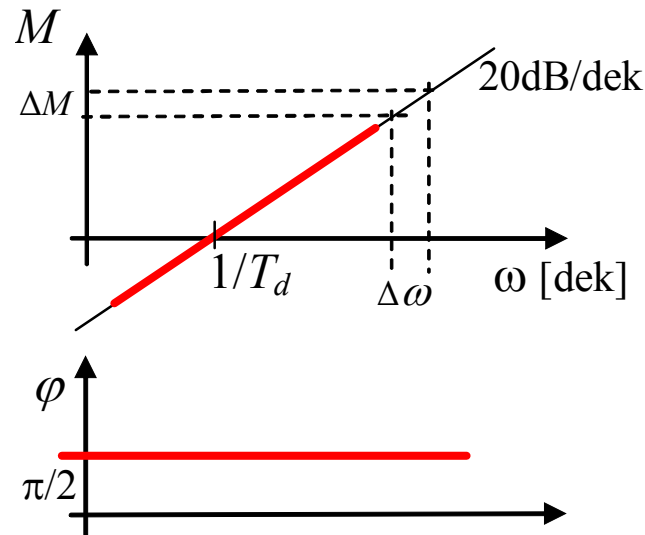
$$Q(\omega) = \omega T_d$$



$$A(\omega) = |j\omega T_d| = \omega T_d$$

$$\varphi(\omega) = \pi/2$$

$$M(\omega) = 20\lg|\omega T_d|$$



Legenda ???

$$M = 0 \rightarrow \omega T_d = 1 \rightarrow \omega = \frac{1}{T_d}$$

$$\frac{\Delta M}{\Delta \omega} = 20\lg(10\omega_1) - 20\lg(\omega_1) = 20\lg \frac{10\omega_1}{\omega_1} = 20 \frac{dB}{dek}$$

**cz. całkujący:**

$$G(s) = \frac{K}{sT_i}$$

$$G(j\omega) = \frac{K}{j\omega T_i} = -j \frac{K}{\omega T_i}$$

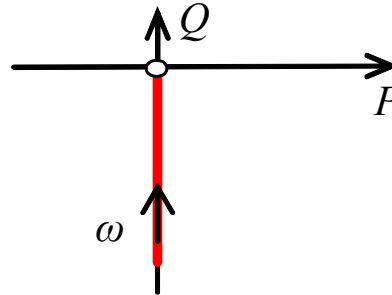
$$P(\omega) + jQ(\omega) = A(\omega)e^{j\varphi(\omega)}$$

$$M(\omega) = 20 \lg A(\omega)$$

$$\varphi(\omega) = \arctg(Q/P)$$

$$P(\omega) = 0$$

$$Q(\omega) = -\frac{K}{\omega T_i}$$

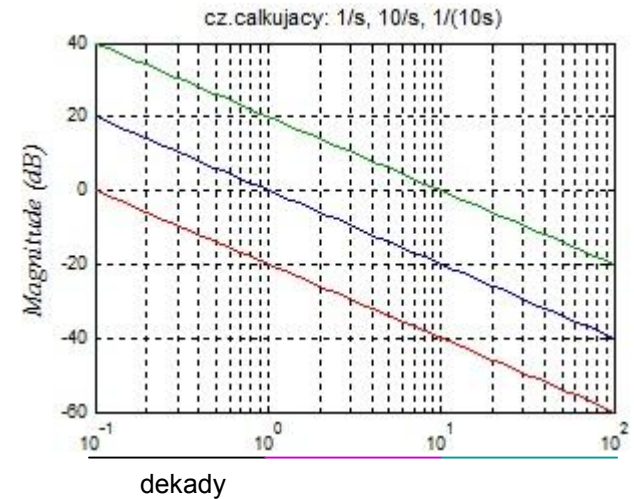
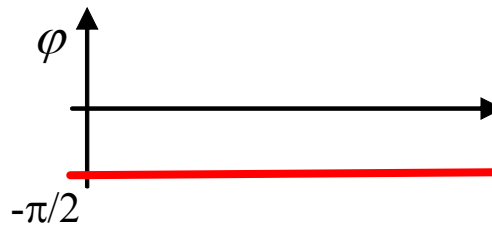
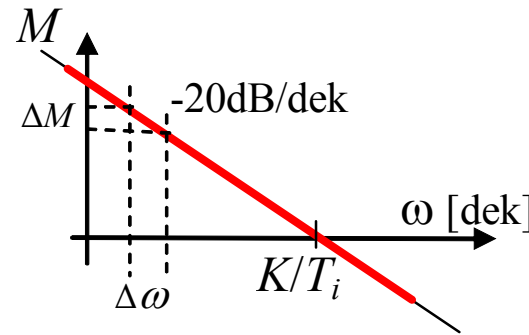


$$A(\omega) = \left| \frac{K}{j\omega T_i} \right| = \frac{K}{\omega T_i}$$

$$\varphi(\omega) = -\pi/2$$

$$M(\omega) = 20 \lg \left| \frac{K}{\omega T_i} \right| =$$

$$= 20 \lg K - 20 \lg \omega - 20 \lg T_i$$



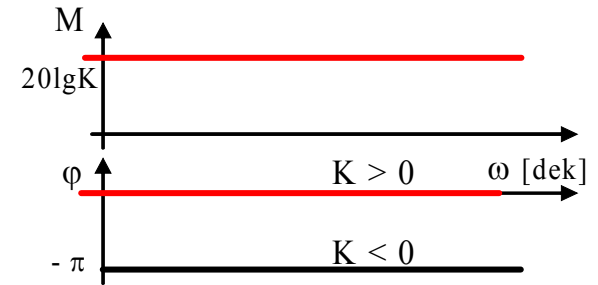
Legenda ???

$$M = 0 \rightarrow \frac{K}{\omega T_i} = 1 \rightarrow \omega = \frac{K}{T_i}$$

$$\frac{\Delta M}{\Delta \omega} = -20 \lg(10\omega_1) + 20 \lg(\omega_1) = 20 \lg \frac{\omega_1}{10\omega_1} = -20 \frac{dB}{dek}$$

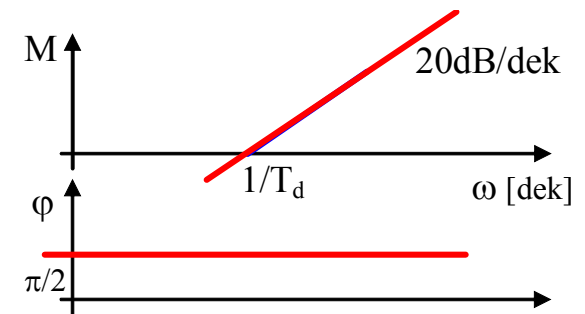
**cz. proporcjonalny:**

$$G(s) = K \quad G(j\omega) = K$$
$$M(\omega) = 20\lg|K|$$



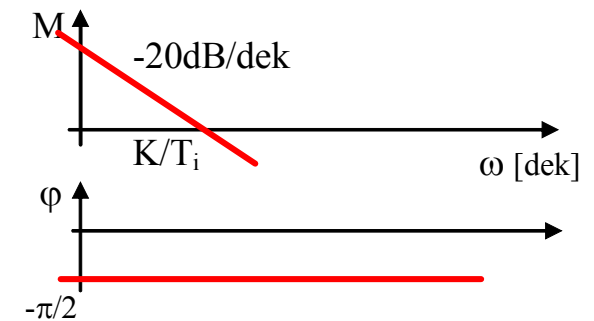
**cz. różniczkowy:**

$$G(s) = sT_d \quad G(j\omega) = j\omega T_d$$
$$M(\omega) = 20\lg|\omega T_d|$$



**cz. całkujący:**

$$G(s) = \frac{K}{sT_i} \quad G(j\omega) = \frac{K}{j\omega T_i} = -j \frac{K}{\omega T_i}$$
$$M(\omega) = 20\lg\left|\frac{K}{\omega T_i}\right|$$



cz. inercyjny:

$$P(\omega) + jQ(\omega) = A(\omega)e^{j\varphi(\omega)}$$

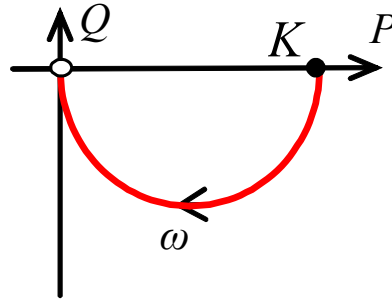
$$M(\omega) = 20 \lg A(\omega)$$

$$\varphi(\omega) = \text{arctg}(Q/P)$$

$$G(s) = \frac{K}{1+sT} \quad G(j\omega) = \frac{K}{1+j\omega T} = \frac{K}{1+\omega^2 T^2} - j \frac{K\omega T}{1+\omega^2 T^2}$$

$$P(\omega) = \frac{K}{1+\omega^2 T^2}$$

$$Q(\omega) = -\frac{K\omega T}{1+\omega^2 T^2}$$

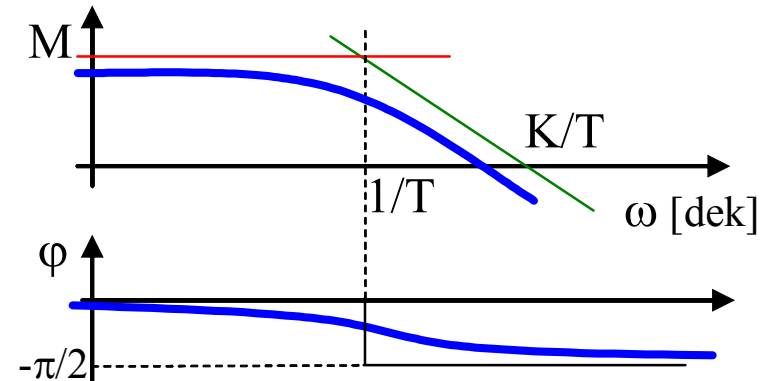


$$A(\omega) = \left| \frac{K}{1+j\omega T} \right|$$

$$\varphi(\omega) = \text{arctg}(-\omega T)$$

dla  $\omega \ll 1/T$      $G(j\omega) \approx \underline{K}$

dla  $\omega \gg 1/T$      $G(j\omega) \approx \underline{\frac{K}{j\omega T}}$





cz. forsujący:

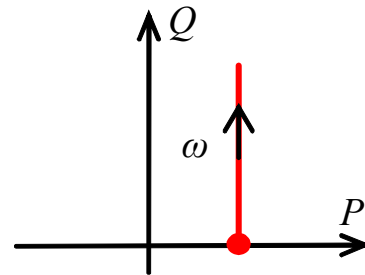
$$G(s) = 1 + sT$$

$$G(j\omega) = 1 + j\omega T$$

$$P(\omega) + jQ(\omega) = A(\omega)e^{j\varphi(\omega)}$$
$$M(\omega) = 20 \lg A(\omega)$$
$$\varphi(\omega) = \arctg(Q/P)$$

$$P(\omega) = 1$$

$$Q(\omega) = \omega T$$



$$A(\omega) = |1 + j\omega T|$$

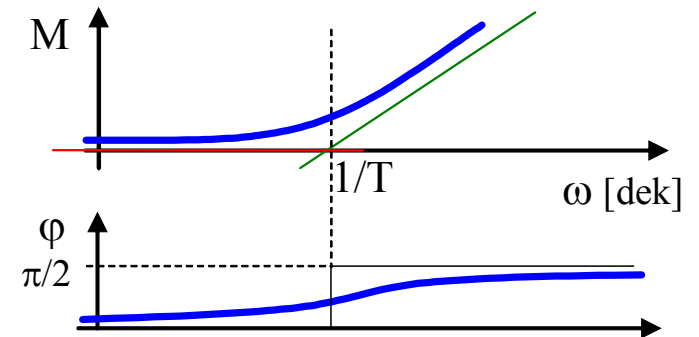
$$\varphi(\omega) = \arctg(\omega T)$$

dla  $\omega \ll 1/T$

$$G(j\omega) \approx 1$$

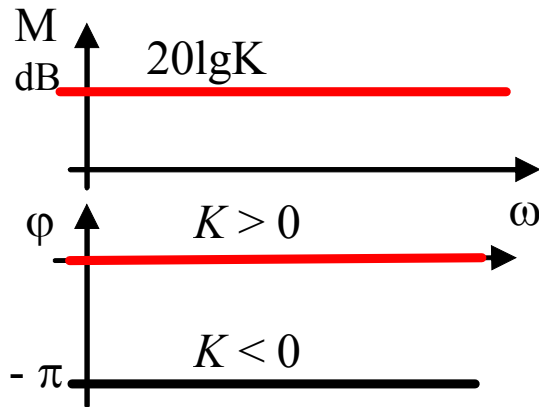
dla  $\omega \gg 1/T$

$$G(j\omega) \approx j\omega T$$

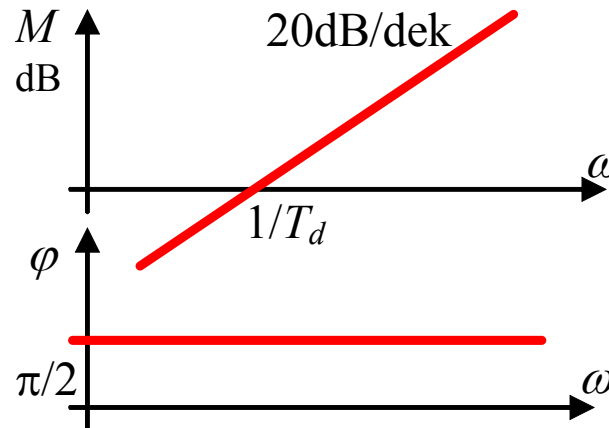


## Logarytmiczne charakterystyki częstotliwościowe (podstawowe)

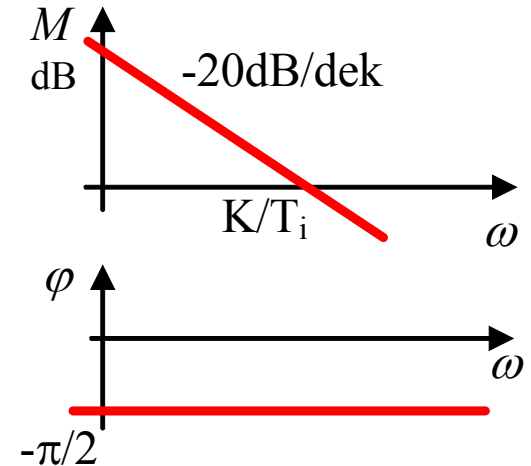
$$G(j\omega) = K$$



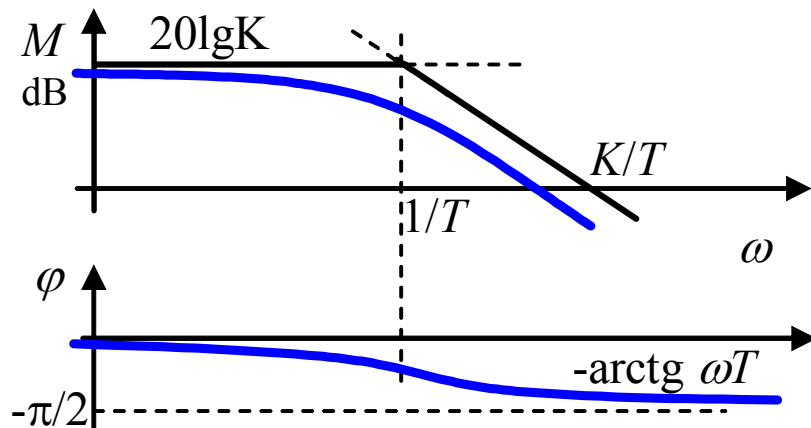
$$G(j\omega) = j\omega T_d$$



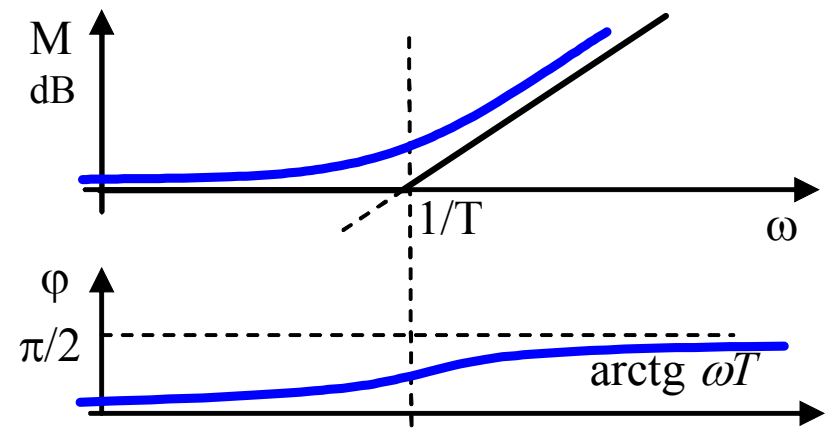
$$G(j\omega) = \frac{K}{j\omega T_i} = -j \frac{K}{\omega T_i}$$



$$G(j\omega) = \frac{K}{1 + j\omega T}$$

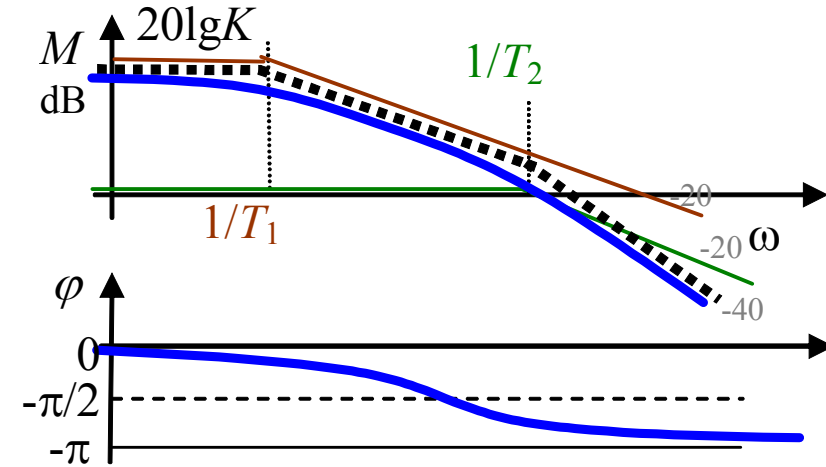
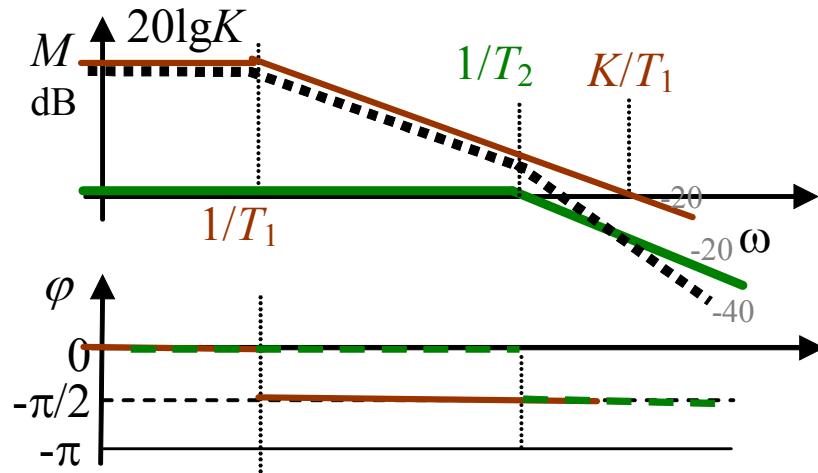


$$G(j\omega) = 1 + j\omega T$$

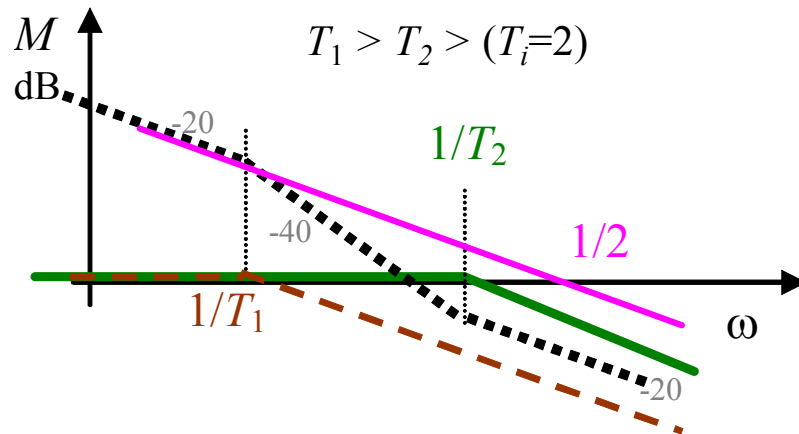


## Logarytmiczne charakterystyki częstotliwościowe (złożone)

$$\frac{K}{(1 + j\omega T_1)(1 + j\omega T_2)}, T_1 > T_2$$

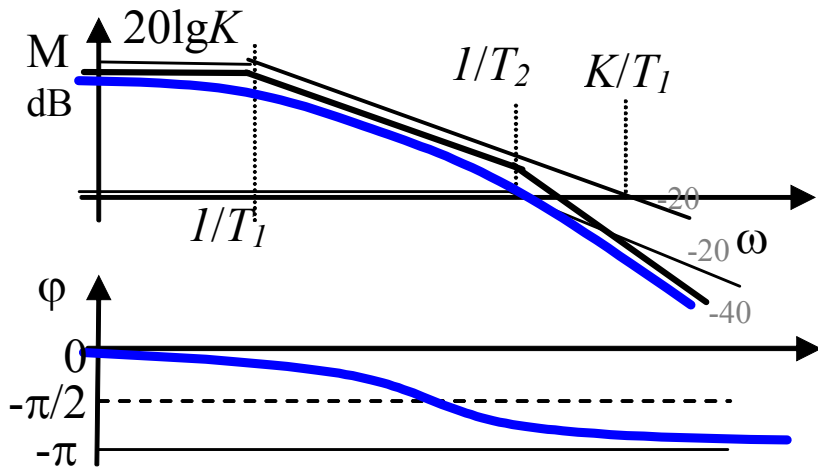


$$\frac{(1 + j\omega T_2)}{2s(1 + j\omega T_1)} = \frac{1}{2s} \frac{1}{(1 + j\omega T_1)} (1 + j\omega T_2)$$

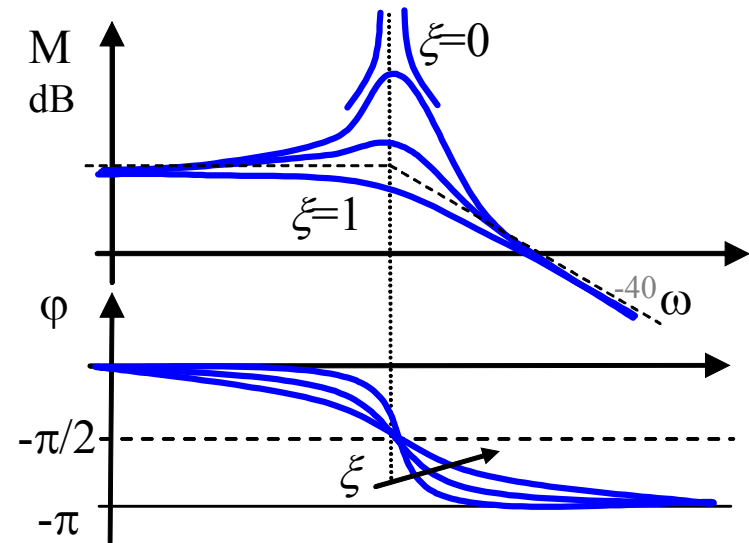


## Logarytmiczne charakterystyki częstotliwościowe (szczególne)

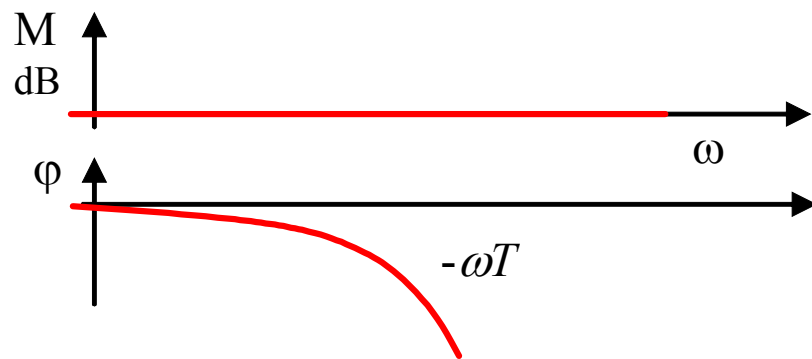
$$\frac{K}{1 + j2\xi T\omega + (j\omega T)^2} = \frac{K}{(1 + j\omega T_1)(1 + j\omega T_2)}, \xi > 1$$



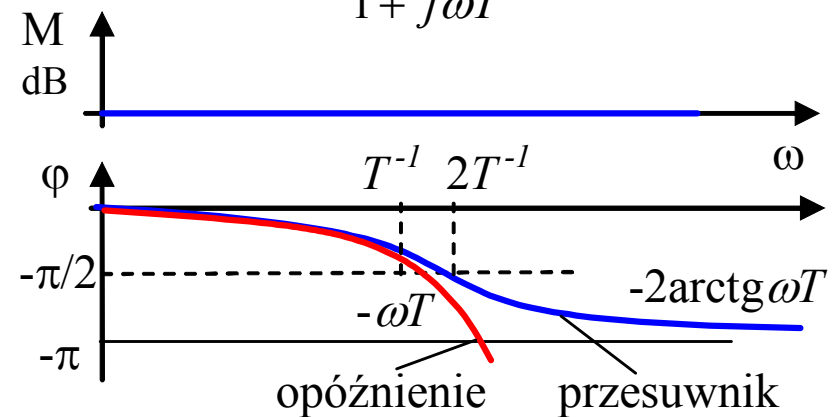
$$\frac{K}{1 + j2\xi T\omega + (j\omega T)^2}, \xi < 1$$



$$G(j\omega) = e^{-j\omega T_o}$$

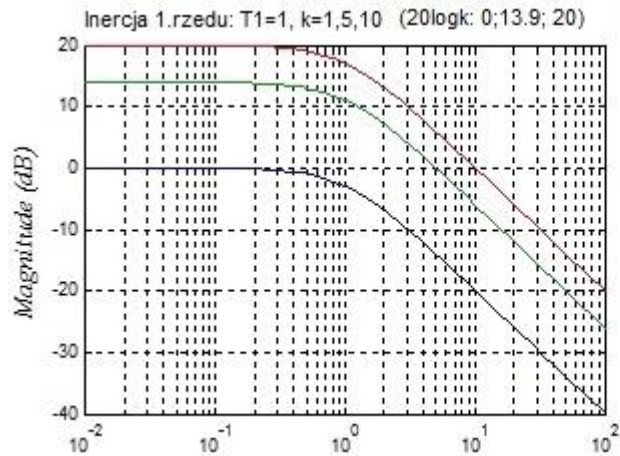


$$G(j\omega) = \frac{1 - j\omega T}{1 + j\omega T}$$

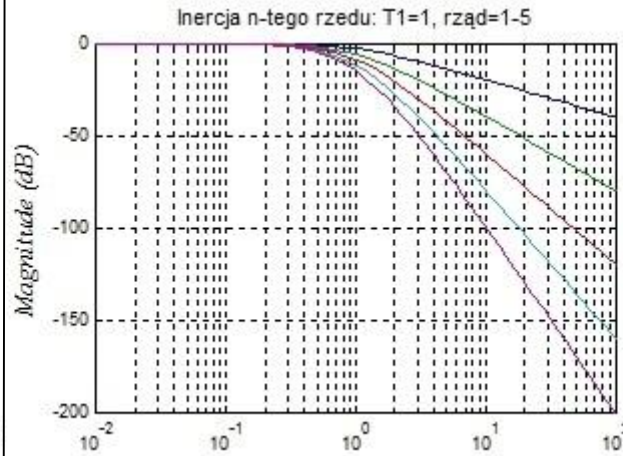


# Charakterystyki częstotliwościowe – wpływ parametrów

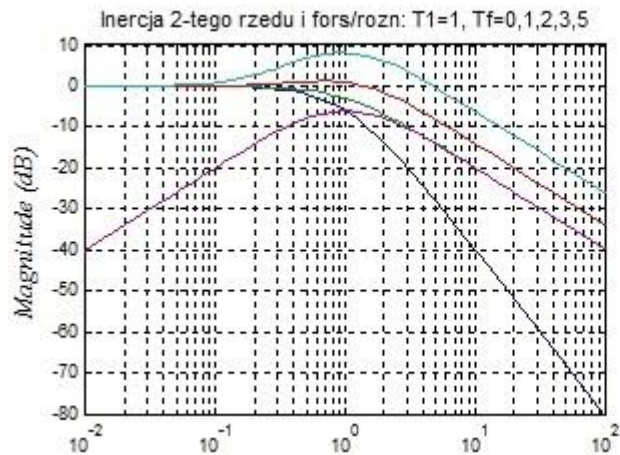
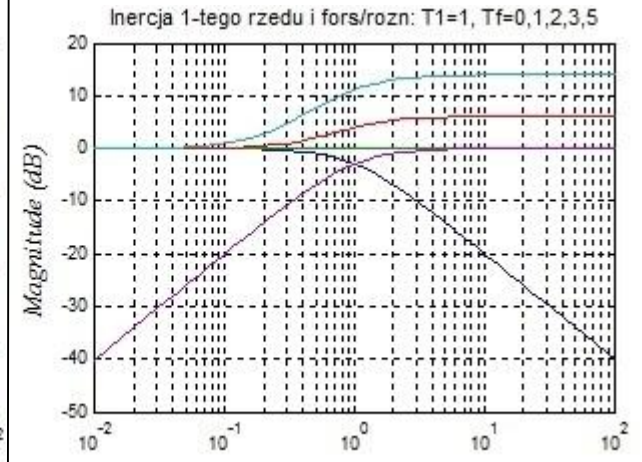
$$\frac{k}{(T_1s + 1)}$$



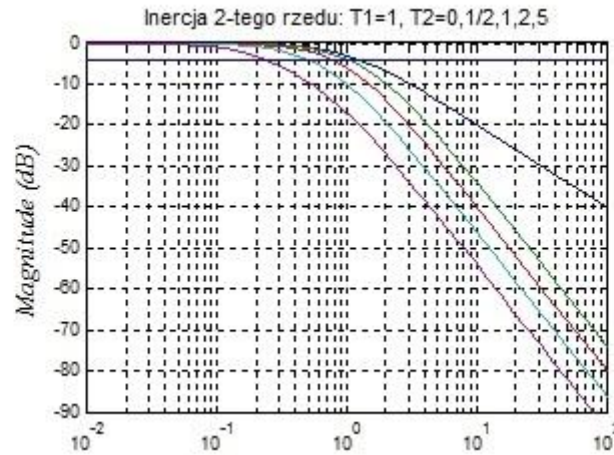
$$\frac{k}{(T_1s + 1)^n}$$



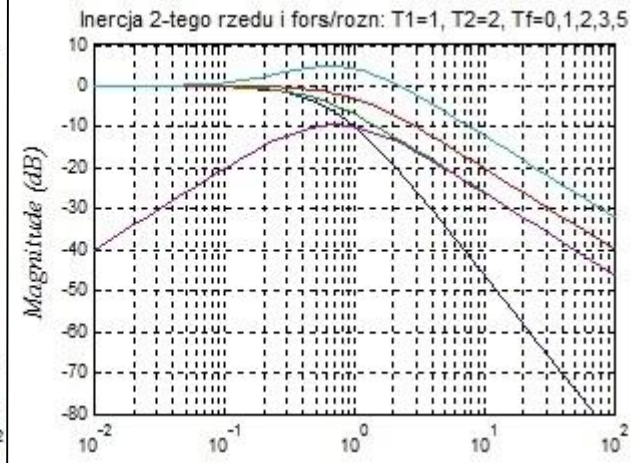
$$\frac{k(T_f s + 1)}{(T_1 s + 1)} \quad \frac{ks}{(T_1 s + 1)}$$



$$\frac{k(T_f s + 1)}{(T_1 s + 1)^2} \quad \frac{ks}{(T_1 s + 1)^2}$$



$$\frac{k}{(T_1 s + 1)(T_2 s + 1)}$$



$$\frac{k(T_f s + 1)}{(T_1 s + 1)(T_2 s + 1)} \quad \frac{ks}{(T_1 s + 1)(T_2 s + 1)}$$

# Regulator PID – charakterystyki częstotliwościowe



**PI:**

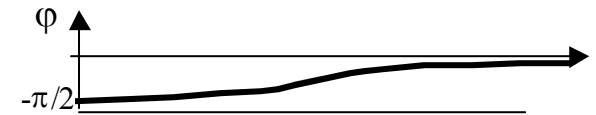
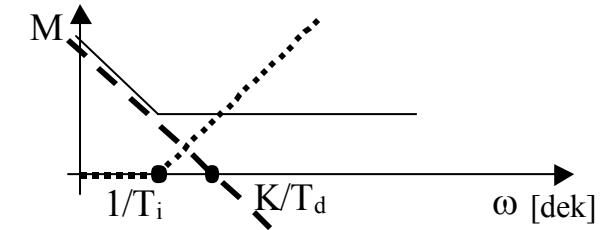
$$G(s) = K \left( 1 + \frac{1}{sT_i} \right)$$

$$G(j\omega) = K - j \frac{K}{\omega T_i}$$

$$M(\omega) = 20 \lg \left| K \frac{1 + j\omega T_i}{j\omega T} \right|$$

$$M(\omega) = 20 \lg \left| \frac{K}{j\omega T} \right| + 20 \lg |1 + j\omega T_i|$$

..... - - - - -



**PD:**

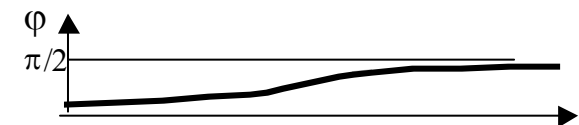
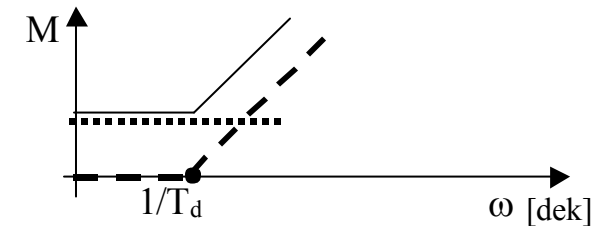
$$G(s) = K(1 + sT_d)$$

$$G(j\omega) = K + j\omega T_d$$

$$M(\omega) = 20 \lg |K(1 + j\omega T_d)|$$

$$M(\omega) = 20 \lg |K| + 20 \lg |1 + j\omega T_d|$$

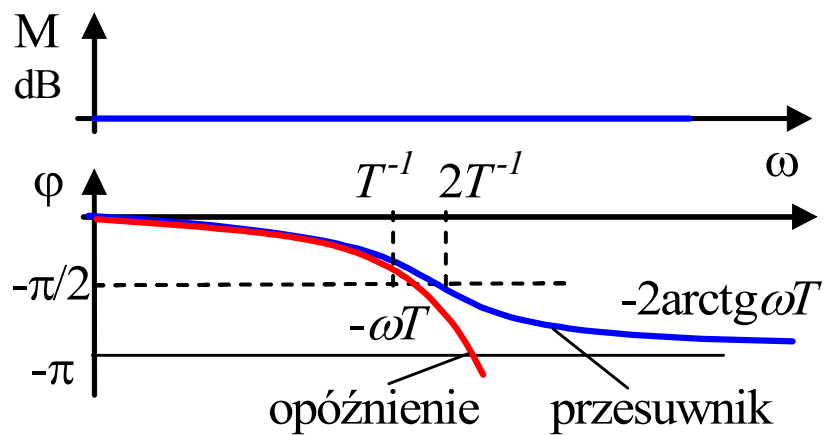
..... - - - - -



# Logarytmiczne charakterystyki częstotliwościowe



## układy minimalnofazowe



## Własności logarytmicznych charakterystyk częstotliwościowych

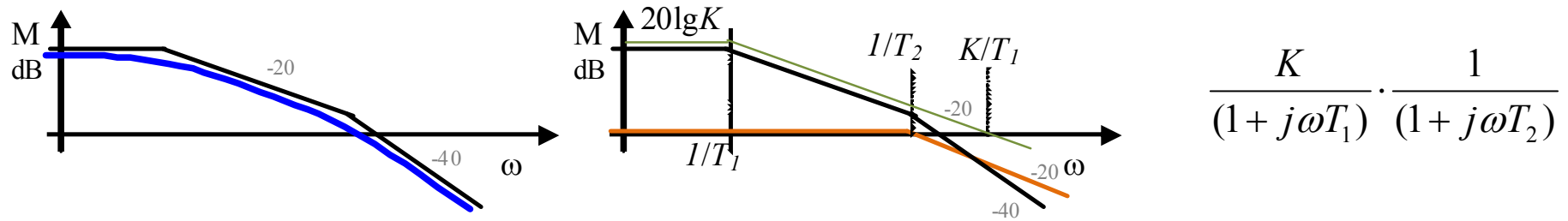
- sumowanie charakterystyk dla członów połączonych szeregowo
- asymptoty charakterystyki amplitudowej – nachylenie +/- 20 dB/dek
- każdy biegun objawia się załamaniem asymptoty o -20 dB/dek
- każde zero objawia się załamaniem asymptoty o +20 dB/dek
- określony maksymalny błąd charakterystyk asymptotycznych członu inercyjnego i forsującego
  - dla częstości załamania popełnia się błąd 3dB
  - w odległości oktawy od częstości załamania – błąd 1 dB
- dla układów minimalnofazowych można otworzyć ch. fazową



# Zdejmowanie charakterystyk częstotliwościowych

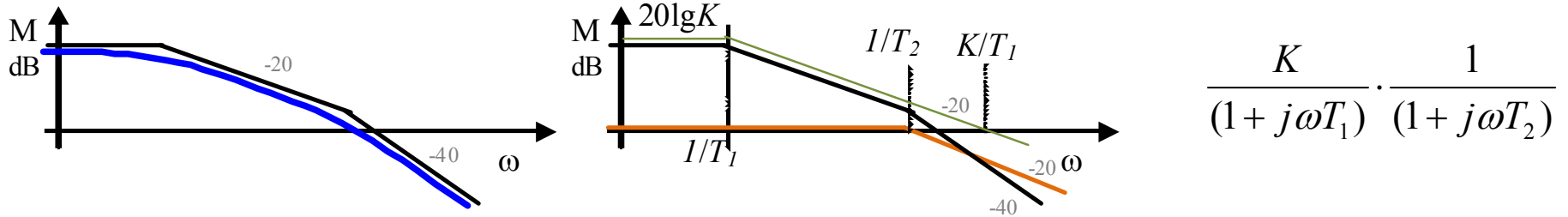
## Opis eksperymentu

## Identyfikacja modelu na podstawie charakterystyk częstotliwościowych

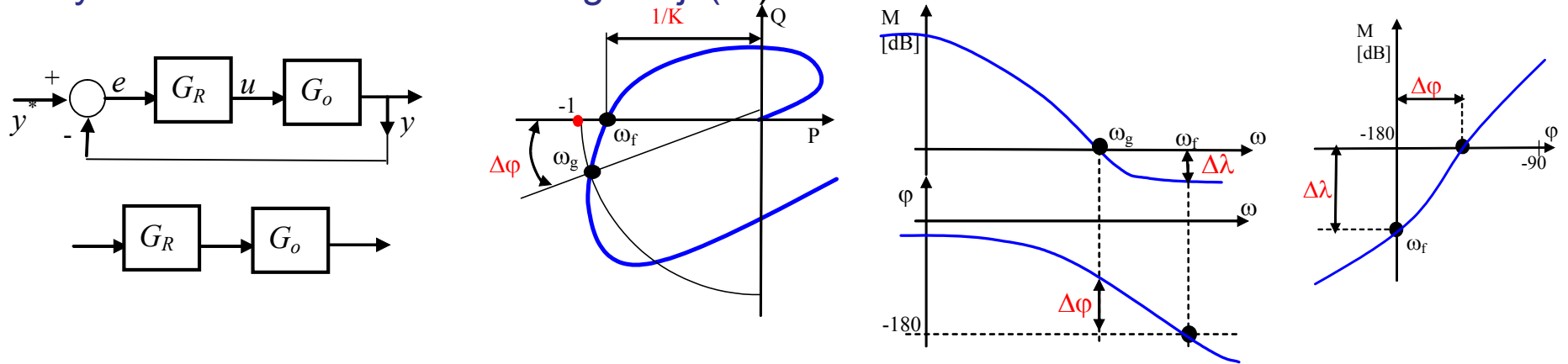


# Zastosowanie charakterystyk częstotliwościowych

- Identyfikacja modelu na podstawie charakterystyk częstotliwościowych



- Kryterium stabilności układu regulacji (✳)



- Projektowanie filtrów (✳)
- Korekcja własności dynamicznych (✳)
  - pasmo przenoszenia
  - kompensacja biegunów